Subject Code-: C4307

M.Tech - I Semester [R09] Regular/Supplementary Examinations, April - 2012 SPECIAL MACHINES AND CONTROL

(Common to P&ID, PE, PE&ED and PE&PS)

Time: 3 Hours

Max Marks: 60

Answer any FIVE questions. All questions carry EQUAL marks.

- 1.a. Briefly explain different modes of excitations of VR stepping motor?
 - b. Draw the static torque curve of VR stepper motor and explain how the torque is produced?
- 2. a. Explain open loop operation of stepper motor? Show the dynamics of the rotor position to move over one step angle?
 - b. Describe why the closed loop control is necessitated over open loop control of stepper motor? [8M+4M]
- 3. a. Derive the torque expression for Switched reluctance motor?
 - b. Briefly discuss with neat diagram, the control of SRM?
- 4. a. Derive the emf equation of PMBLDC motor?
 - b. Draw and explain the speed-torque characteristics of PMBLDC motor?
- 5 Discuss with neat diagrams, how the vector control scheme is adapted in permanent magnet synchronous motor?
- 6. a. Draw and explain the characteristics of various servomotors? Show the regions of control for the suitability of applications?
 - b. Describe the microprocessor based applications of servomotors? [8M+4M]
- 7. a. Describe the schematic diagram of ac tachometer and hence explain its principle?
 - b. An a.c. tachometer having instrument constant of 50Hz per rev/min is connected to a device having instrument constant of 0.02 V/Hz that converts the frequency into millivolts and then another device having instrument constant of 0.05 mV/mA that converts millivolts into milliamps. Write down the overall relationship between current and speed. Calculate the output when the input speed is 900 rev/min.
- 8. a. Discuss goodness factor of linear induction motor? How it can be improved?
 - b. With the help of schematic diagram explain the control technique of DCLM?